# A variational approach to the macroscopic electrodynamics of hard superconductors

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Torino, July 4, 2006, joint meeting U.M.I.-S.M.F.

Joint work with Annalisa Malusa

## Outline

#### Superconductivity

- Introduction
- Macroscopic electrodynamics

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#### Quasistatic evolution

- Discretized Faraday's law
- Magnetic and electric field

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Introduction Macroscopic electrodynamics

## Penetration of external magnetic field

= penetrated magnetic field



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Introduction Macroscopic electrodynamics

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Introduction Macroscopic electrodynamics

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- Mixed state: partial penetration in the bulk.
- Normal conducting phase: full penetration in the bulk.

## Advantages of type-II superconductors

Technological advantages of type-II superconductors in mixed state:

- high  $T_c$  (up to 135K)
- superconductivity properties with large magnetic fields
- current flow in the bulk of the sample (not only in thin layers)

Introduction Macroscopic electrodynamics

#### Models for type-II superconductors

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## Models for type-II superconductors

- Microscopic: BCS theory (Bardeen, Cooper, Schrieffer 1957), quantum mechanical description.
- Mesoscopic: Ginzburg-Landau model (1950); formation of vortices (filaments), Abrikosov (1957).
- Macroscopic: Bean's model (1962), critical state model for the description of macroscopic electrodynamics.

Bean's model (C.P. Bean, 1962) for type-II hard superconductors: exists a critical current  $J_c$  such that:

- $|\vec{J}| = J_c$  in the region penetrated by the magnetic field;
- $\vec{J} = 0$  otherwise.

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Anisotropy of  $J_c$ , due to Cu-O planes, structure of defects, etc: exists  $\Delta \subset \mathbb{R}^3$  compact convex containing a neighborhood of 0 s.t.

*J* ∈ ∂Δ, in the region penetrated by the magnetic field; *J* = 0 otherwise.

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#### Macroscopic electrodynamics

**PROBLEM**: given a superconductor  $Q \subset \mathbb{R}^3$  in an external field  $\vec{H}_S(t)$ , find the internal magnetic field  $\vec{H}(x, t)$  and the electric field  $\vec{E}(x, t)$ . (Boundary condition:  $\vec{H} = \vec{H}_S$  on  $\partial Q$ .)

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- anisotropic conductor:  $\vec{E}(\vec{J}) = A \vec{J}$ , A = resistivity tensor

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In the isotropic case, the constraint  $|\vec{J}| \leq J_c$  can be described by a vertical  $\vec{E} - \vec{J}$  relation:



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The electric field is determined using the additional condition  $\vec{E} || \vec{J}$ .

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• Start from an anisotropic power law approximation for the dissipation  $\vec{E} \cdot \vec{J}$ :

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- In the limit as  $p \to \infty$ :  $\vec{E}(\vec{J}) \in \partial I_{\Delta}(\vec{J})$   $\partial I_{\Delta}(\vec{J}) = \begin{cases} \{0\}, & \text{if } \vec{J} \in \text{interior of } \Delta, \\ \{\lambda D \rho_{\Delta}(\vec{J}); \ \lambda \ge 0\}, & \text{if } \vec{J} \in \partial \Delta, \\ \emptyset, & \text{if } \vec{J} \notin \Delta \end{cases}$ subdifferential of the indicator function of  $\Delta$ .  $\Longrightarrow$  gives the constraint  $\vec{J} \in \Delta$ .

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Rigorous giustification by Γ-convergence.

Introduction Macroscopic electrodynamics

## Cylindrical symmetry

- $Q = \Omega \times \mathbb{R}$ , cylinder with cross-section  $\Omega \subset \mathbb{R}^2$ , smooth;
- $\vec{H}_{S}(t) = (0, 0, h_{S}(t))$  directed along the axis of the cylinder.

Introduction Macroscopic electrodynamics

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Introduction Macroscopic electrodynamics

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$$\implies \text{By symmetry: } \vec{H}(x,t) = (0,0,h(x_1,x_2,t))$$
$$\implies \vec{J} = \text{curl } \vec{H} = (\partial_{x_2}h, -\partial_{x_1}h, 0)$$
  
Remark:  $\vec{J} \in \Delta \iff Dh \in K$ , where  $K \subset \mathbb{R}^2$  is the rotation of the section  $z = 0$  of  $\Delta$ .
Discretized Faraday's law Magnetic and electric field

#### Quasistatic evolution

Time discretization in [0, T]: 
$$\delta t = T/n$$
,  $t_i = i\delta t$ ,  
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 $\implies$  admits the variational formulation

$$J_p(h) = \int_{\Omega} \frac{1}{p} \left[ \rho(Dh) \right]^p + \frac{\mu_0}{2c\delta t} (h-h_i)^2, \qquad h \in h_s(t_{i+1}) + W_0^{1,p}(\Omega)$$

i.e.,  $h_{i+1}$  is the unique minimum point of  $J_p$  in  $h_s(t_{i+1}) + W_0^{1,p}(\Omega)$ .  $\rho = \rho_K = \text{gauge function of } K \subset \mathbb{R}^2$ .

# Convergence

#### Theorem (G.C. - A. Malusa)

 $u_p \in h_s(t_{i+1}) + W_0^{1,p}(\Omega)$ : unique minimum point of  $J_p$ ,  $p \ge 1$ .  $u_\infty \in h_s(t_{i+1}) + W_0^{1,1}(\Omega)$ : unique minimum point of

$$J(u) = \int_{\Omega} I_{\mathcal{K}}(Du) + (u - h_i)^2, \qquad u \in h_s(t_{i+1}) + W_0^{1,1}(\Omega).$$

Then, for every q > 1,  $(u_p)$  converges to  $u_\infty$  in weak- $W^{1,q}$ .

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Conclusion: the variational formulation of Bean's law is based on functional *J*. Given  $h_i$ , we have  $h_{i+1} = u_{\infty}$ .

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**Conclusion**: the variational formulation of Bean's law is based on functional *J*. Given  $h_i$ , we have  $h_{i+1} = u_{\infty}$ . **Remark**: variational formulation proposed by Badía-López (2002) starting from physical considerations.

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Discretized Faraday's law Magnetic and electric field

#### Necessary conditions - Electric field

Theorem (Dual function)

 $\exists$  a non-negative continuous function  $v_i$  such that

$$-\operatorname{div}(v_i D
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Techniques developed in G.C., Malusa: to appear in Trans. Amer. Math. Soc. Isotropic case (K =ball): Cannarsa, Cardaliaguet, G.C., Giorgieri: Calc. Var. 2005

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Discretized Faraday's law Magnetic and electric field

#### Candidate solution $u_{\infty} = h_{i+1}$

Minkowski distance w.r.t.  $K: d(x) = \min_{y \in \partial \Omega} \rho_K^0(x - y)$ 

 $(\rho_K^0 = \text{polar of the gauge function of } K)$ 

 $\implies$  viscosity solution of  $\rho(Du) = 1$  in  $\Omega$ , u = 0 on  $\partial \Omega$ .

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Minkowski distance w.r.t. 
$$-K$$
:  
 $d^{-}(x) = \min_{y \in \partial \Omega} \rho^{0}_{-K}(x - y) = \min_{y \in \partial \Omega} \rho^{0}_{K}(y - x)$   
 $\implies$  viscosity solution of  $-\rho(Du) = -1$  in  $\Omega$ ,  $u = 0$  on  $\partial \Omega$ .

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#### Solution of the minimum problem:

$$h_{i+1}(x) = egin{cases} d(x) + h_s(t_{i+1}), & ext{if } x \in \Omega^+ = \{h_i > d\}, \ -d^-(x) + h_s(t_{i+1}), & ext{if } x \in \Omega^- = \{h_i < -d^-\}, \ h_i(x), & ext{if } x \in \Omega^0 = \Omega \setminus (\Omega^+ \cup \Omega^-). \end{cases}$$

 $h_{i+1}(x) = [h_i(x) \lor (-d^-(x) + h_s(t_{i+1}))] \land (d(x) + h_s(t_{i+1}))_{\mathbb{R}}, \mathbb{R}$ 

Discretized Faraday's law Magnetic and electric field

# 1D heuristics

$$K = [-1, 2]$$
$$J(h) = \int_{\Omega} |h - h_i|^2 + I_K(Dh)$$
$$h = 0 \text{ on } \partial\Omega$$



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Discretized Faraday's law Magnetic and electric field

# 1D heuristics

$$egin{aligned} \mathcal{K} &= [-1,2] \ \mathcal{J}(h) &= \int_{\Omega} |h-h_i|^2 + \mathcal{I}_{\mathcal{K}}(Dh) \ h &= 0 ext{ on } \partial \Omega \end{aligned}$$



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#### Decomposition of $\Omega$ in transport rays

 $\Omega$  can be decomposed in transport rays (paths of minimal distance from the boundary):

two possible decompositions, one for d and one for  $d^-$ .

Discretized Faraday's law Magnetic and electric field

#### Decomposition of $\Omega$ in transport rays

 $\Omega$  can be decomposed in transport rays (paths of minimal distance from the boundary): two possible decompositions, one for d and one for  $d^-$ . Example:  $h_i(y) > 0$ .

 $\begin{array}{c}
 \rho \\
 point on cut locus \\
 v(y) \\
 y \\
 D_{D\rho}(v(y)) \\
 transport ray \\
 v(y) = inward Euclidean normal of <math>\partial\Omega$  at y $l(y) = length of the transport ray
\end{array}$ 

 $\implies$  on each transport ray apply the 1D-heuristics.

• Start with  $h(x,0) = h_0(x) \in \operatorname{Lip}_{\mathcal{K}}(\Omega)$ ,  $h_0 = h_{\mathcal{S}}(0)$  on  $\partial \Omega$ .

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$$h_{i+1} = \text{internal magnetic field at time } t_{i+1}$$
  
 $\implies$  solution of the minimization problem  
 $\min\left\{\int_{\Omega} \frac{\mu_0}{2} |h - h_i|^2 + \delta t I_K(Dh); h \in h_S(t_{i+1}) + W_0^{1,1}(\Omega)\right\}$ 

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- By the existence and uniqueness theorem,  $h_{i+1}(x) = \left[h_i(x) \lor \left(h_S(t_{i+1}) - d^-(x)\right)\right] \land \left(h_S(t_{i+1}) + d(x)\right)$

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- Explicit formula for monotone external field:
  - 1.  $h_S$  monotone increasing in [0, T]:

 $h_i(x) = h_0(x) \lor (h_S(t_i) - d^-(x))$ 2.  $h_S$  monotone decreasing in [0, T]:

 $h_i(x) = h_0(x) \wedge (h_S(t_i) + d(x))$ 

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For  $\delta t = T/n$ ,  $n \in \mathbb{N}^+$ , construct  $h_i$  as above and define  $h^n(x, t) = h_i(x)$ , for  $t \in [t_i, t_{i+1})$ 

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•  $h_S$  decreasing:  $h^n(x, t) \rightarrow h(x, t) = h_0(x) \land (h_S(t) + d(x))$  $\rightarrow$  the internal magnetic field can be explicitly computed if  $h_S$  is

 $\implies$  the internal magnetic field can be explicitly computed if  $h_S$  is piecewise monotone.

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# Example



The section  $\Omega$ , the constraints set K; Level sets and 3D-plot of the distance d.

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# Example: plot of h



 $\dot{t_4}$ 

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 $t_5 \quad t_6 = T$ 

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Magnetic and electric field

# Example: plot of h



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# Example: plot of h



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# Example: plot of h



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Discretized Faraday's law Magnetic and electric field

# Example: plot of h





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Magnetic and electric field

# Example: plot of h



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#### Hysteresis loop



Hysteresis loop: magnetization  $\vec{M} = \langle \vec{H} \rangle - \vec{H}_S$  versus external field  $\vec{H}_S$ .

- **→** → **→** 

Superconductivity Quasistatic evolution

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#### Example: plot of w



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• Strong mathematical justification of the anisotropic variational formulation of Bean's law suggested by Badía and López.

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...and what remains to do:

- Nonhomogeneous samples (general Finsler metric instead of Minkowski); connections with elasticity theory and material science (e.g., dieletric breakdown).
- True 3D analysis (no cylindrical symmetry).