

Lecture 4 A hierarchy of plate models
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 185-236

$$I^h(y) = \int_{\mathbb{R}^2} W(\nabla_h y) dx$$

$$\nabla_h y = \left(y_{,1} / y_{,2} / \frac{1}{h} y_{,3} \right)$$

$$J^h(y) = I^h(y) - \int_{\mathbb{R}^2} f^{(e)} \cdot y$$

$$\int_{\mathbb{R}^2} f^{(e)} = 0.$$

Q1. If $I^h(y^{(e)}) \sim h^\beta$ what can be said about $y^{(e)}$?

Q2. If $f^{(e)} \sim h^\alpha$ what can be said about (optimal) minimizers of $J^h(y^{(e)})$?

First three cases

$\alpha = 2 \implies \beta = 2 \implies$ Kirchhoff's plate theory.

$\beta = 2$ bubble case

$\beta < 2 \implies$ non-compactness (by wrinkling)
 $\beta = 2 \implies y^{(e)} \rightarrow \bar{y}$ isometric immersion
 $\beta > 2 \implies y^{(e)} \rightarrow$ affine isometry.

$$\text{Today } \left\{ \begin{array}{l} \beta = 0 \quad (\alpha = 0) \\ \beta = 4. \quad (\text{which } \alpha ?) \end{array} \right.$$

2.1

Theorem 6 (LeDret - Result; $\beta = 0$) Suppose

$$C(|F|^2 - 4) \leq W(F) \leq C(|F|^2 + 4) \quad (*)$$

Then:

$$(i) \text{ If } I^h(y^{(h)}) \leq C, \text{ then}$$

$$y^{(h)} \rightarrow \bar{y} \quad W^{1,2}(\text{near } \bar{y}), \quad \bar{y}_3 = 0$$

$$\liminf I^h(y^{(h)}) \geq \int_{\Omega} W_{\text{min}} \quad (\nabla \bar{y}) dx' \\ = I_{\text{min}}(\bar{y})$$

$$(ii) \forall \bar{y} \in W^{1,2}(S; \mathbb{R}^3) \exists y^{(h)} \rightarrow \bar{y} \quad W^{1,2}.$$

$$e(I^h(y^{(h)})) \rightarrow I_{\text{min}}(\bar{y})$$

Corollary 7. ($\alpha = 0$) For $\alpha \neq 1$, set

$$f^{(h)} \rightarrow f \quad \text{in } L^p.$$

Then

$$\text{Almost min. of } I^h \rightarrow \text{minimizers of } \bar{I}_{\text{min}}.$$

What is W_{mem} ? (Think!)

$$G \in \mathbb{R}^{3 \times 2}$$

$$W_2(G) = \min_{a \in \mathbb{R}^3} W(G|a)$$

$$W_{\text{mem}} = W_2 \circ \mathcal{QC} \quad \text{quasi-compression}$$

If $W(\text{Id}) = \min W = 0$ + formal diff.

$$\Rightarrow W(G) = 0 \quad \forall G \text{ w.t. } G^T G \leq \text{Id}$$

\Rightarrow No resistance to compression.

\Rightarrow Tensor-field theory (... , Pipkin).

$\beta = 4$ Vag formal expansion \rightarrow von Kärman
plate theory


\rightarrow Sticks

Circalet & Destuyvel '80: Formal asymptotics.

≥ 500 papers on vK eqns.

Idea behind vK: Linearize Kirchhoff ansatz

$$y^{(0)} = \bar{y}(x') + h x_3 \nu(x'), \quad \nu = \bar{y}_{,1} \wedge \bar{y}_{,2}$$



$$\bar{y} = \begin{pmatrix} x' \\ 0 \end{pmatrix} + \begin{pmatrix} h^2 u \\ h \nu(x') \end{pmatrix}, \quad y_{,1} = \begin{pmatrix} 1 + h^2 u_{,1} \\ 0 \\ h \nu_{,1} \end{pmatrix}$$

$$\nu = \bar{y}_{,1} \wedge \bar{y}_{,2} \approx e_3 - h \begin{pmatrix} \nu_{,1} \\ \nu_{,2} \\ 0 \end{pmatrix}$$

$$A_{ij} = -y_{,ij} \cdot \nu \approx h \nu_{,ij} \quad (i, j \in \{1, 2\})$$

$$\left[\left(\nabla_{h y} \right)^T \nabla_{h y} \right]_{ij}(x', 0) = \delta_{ij} + h^2 \nu_{,i} \nu_{,j} + 2h^2 u_{,ij}$$

$$\begin{aligned} \left(\nabla_{h y} \right)^T \nabla_{h y} \Big|_{x_3=0} &= h^2 \nu_{,i} \nu_{,j} + 2h^2 u_{,ij} \\ &= h^2 \left(\nu \otimes \nu + 2x_3 \nabla^2 \nu \right)_{ij} \end{aligned}$$

$$\begin{aligned} \frac{1}{h^4} \int W(\nabla u, \nabla v) &\approx \frac{1}{2} \int \mathbb{O}_2 \left(\text{sym} \nabla u + \frac{\nabla u \otimes \nabla v}{2} \right) \\ &\quad + \frac{1}{2^*} \int \mathbb{O}_2(\nabla v^2) \\ &= \overline{I}_{VK}(u, v) \end{aligned}$$

Now add u

Remarks \mathbb{O}_2 quadratic \rightarrow linear constitutive relation
 \overline{I}_{VK} not quadratic \rightarrow geometric nonlinearity
 \mathbb{O}_2 instead of \mathbb{O}_3 only central components of \mathbb{O}_3 structure!

Theorem 8. Spse $\overline{I}^h(y^{(e)}) \in C^h$

Then

(i) (arbitrary free Gauss sol.)
 \exists constants $\overline{R}^{(e)} \in SO(3), c^{(e)} \in \mathbb{R}^3$

(1) s.t. $y^{(e)} = (\overline{R}^{(e)})^T y - c^{(e)} \rightarrow \overline{y} = \begin{pmatrix} x' \\ 0 \end{pmatrix} \in W^{1,2}$

(2) $v^{(e)} = \frac{1}{h} \int_{-1/2}^{1/2} y_3^{(e)} dx_3 \rightarrow v \in W^{1,2}, v \in W^{2,2}$

(3) $u^{(e)} = \frac{1}{h^2} \int \begin{pmatrix} y_1^{(e)} - x_1 \\ y_2^{(e)} - x_2 \end{pmatrix} dx_3 \rightarrow u \in W^{1,2}$

$$\liminf \frac{1}{h^4} \overline{I}^h(y^{(e)}) \geq \overline{I}_{VK}(u, v)$$

(ii) upper bound. Given $u \in W^{1,2}(S; \mathbb{R}^2), v \in W^{1,2}(S)$
 $\exists y^{(e)}$ s.t. (1) - (3) hold as

$$l.i. \frac{1}{h^4} \overline{I}^h(y^{(e)}) = \overline{I}_{VK}(u, v)$$

GF, RDJ, ST CRAS 335 (2002), 201-206

R. Monneau AKMA
165 (2003), 1-39.

Ingredients of proof.

① (Scaled) rigidity estimate

② Convergence of $v^{(h)}$ and $\text{Sym} \nabla u^{(h)}$

③ Identification of Guntig strain \mathbb{G}

$$\mathbb{G}^{(h)} = \frac{(R^{(h)})^T \nabla_h u^{(h)} - \text{Id}}{h^2} \rightarrow \mathbb{G}$$

① Theorem Let

$$E_h = \int_{\Omega} \text{dist}^2(\nabla_h u^{(h)}, \text{SO}(3))$$

and suppose that

$$h^{-2} E_h \rightarrow 0 \quad (*)$$

Then $\exists R^{(h)}: \Omega \rightarrow \text{SO}(3)$ s.t.

$$\|\nabla_h u^{(h)} - R^{(h)}\|_{L^2}^2 \leq C E_h, \quad (4)$$

$$\|\nabla R^{(h)}\|_{L^2}^2 \leq C h^{-2} E_h. \quad (5)$$

Proof. "As before". Turn difference quotient estimate into ∇ -estimate by convolution (and projection back to $\text{SO}(3)$). For this one uses (*) and $n=3$. Same care needed near $\partial\Omega$.

(2) Lemma 40 Assumptions + notation as in Thm. Then $\exists R^{(\epsilon)} : S \rightarrow SO(3)$

$$\| \nabla_{g^{(\epsilon)}} - R^{(\epsilon)} \|_{L^2} \leq C \epsilon^2, \quad (6)$$

$$\| R^{(\epsilon)} - \text{Id} \|_{W^{2,2}} \leq C \epsilon \quad (7)$$

$$\frac{R^{(\epsilon)} - \text{Id}}{\epsilon} \rightarrow A \quad W^{2,2}, \quad A^T = -A \quad (8)$$

$$2 \text{sym} \frac{R^{(\epsilon)} - \text{Id}}{\epsilon^2} \rightarrow A^2 \quad L^p, \forall p < \infty \quad (9)$$

$$v^{(\epsilon)} \rightarrow v \quad W^{2,2}, \quad v \in W^{2,2} \quad (10)$$

$$u^{(\epsilon)} \rightarrow u \quad W^{1,2} \quad (11)$$

$$A = A = \begin{pmatrix} 0 & 0 & -v_{,4} \\ 0 & 0 & -v_{,2} \\ v_{,4} & v_{,2} & 0 \end{pmatrix} \quad (12)$$

Proof. Step 1

$$\text{Thm.} \Rightarrow (5) \quad \text{and} \quad \| \nabla R^{(\epsilon)} \| \leq C \epsilon$$

$$\text{Hence} \quad \| R^{(\epsilon)} - \text{const}^{(\epsilon)} \|_{W^{1,2}} \leq C \epsilon, \quad \text{with}$$

$$\text{Wlog} \quad \text{const} = \text{Id}, \quad (\text{by choice of } R^{(\epsilon)}).$$

→ L^p .

Step 2 $A^{(e)} = \frac{R^{(e)} - \text{Id}}{e}$, $A^{(e)} \xrightarrow{(7)} A \text{ in } L^2$

$$\text{Id} = (\text{Id} + hA^{(e)})^T (\text{Id} + eA^{(e)}) = \text{Id} + e(A^{(e)})^T A^{(e)} + R^2(A^{(e)})^T A^{(e)}$$

$$2 \text{sgn} A^{(e)} = A^{(e)} + (A^{(e)})^T = -R(A^{(e)})^T A^{(e)} = R(A^{(e)})^2$$

$$\Rightarrow A + A^T = 0 \quad \text{od} \quad (9)$$

Step 3 (c) + (8)

$$\Rightarrow \frac{\nabla_h y^{(e)} - \text{Id}}{h} \xrightarrow{(8)} A \text{ in } L^2$$

$$v_{3,i}^{(e)} = \frac{1}{h} \int y_{3,i}^{(e)} \rightarrow A_{3i} \text{ in } L^2. \quad (*)$$

Step 4. (6) + (5)

$$\| \text{sgn} \frac{\nabla_h y^{(e)} - \text{Id}}{h^2} \|_{L^2} \leq C_1.$$

$$\Rightarrow \| \text{sgn} \nabla_h u^{(e)} \|_{L^2} \leq C_1.$$

Korn (+ some other) \Rightarrow (11).

Step 5 (*) $\Rightarrow A_{3i} = v_i$, (11) $\Rightarrow A_{12} = 0$.

(3) 1 Set $G^{(e)} = \frac{(R^{(e)})^T \nabla_{x_3}^{-1} e - Id}{R^2}$

By (6) $G^{(e)} \rightarrow G \quad L^1$

Lemma 11 The 2×2 submatrix G'' satisfies

$$G''(x', x_3) = G_0(x') + x_3 G_1(x')$$

where

$$\text{sym } G_0 = \text{sym } \nabla' u + \frac{1}{2} \nabla' v \otimes \nabla' v$$

$$G_1 = -(\nabla')^2 v$$

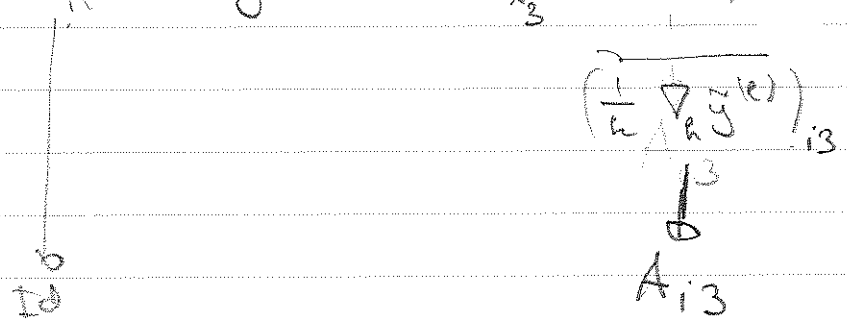
Lemma 11 \Rightarrow Thm. 8 (i) : Classical Taylor expansion (as before).

Rem (Truesdell) Lemma 11 proves that strain vanishes linear in x_3 .

Proof of Lemma 1 $x_3 G_1 \rightsquigarrow$ as before

$$H^{(e)}(x', x_3) = G^{(e)}(x', x_3 + s) - G^{(e)}(x')$$

$$\left(R^{(e)} H^{(e)} \right)_{ij} = \left(\frac{1}{R^2} \int_{x_3}^{x_3+s} \frac{1}{R^2} \dot{\gamma}_{i,3}^{(e)} \right)_{ij}$$



$$H_{ij} = S A_{i3, j} = -S v_{,ij}$$

For G_0 steady

$$(R^{(e)}) \int_{-\frac{1}{2}}^{\frac{1}{2}} \sigma_{ij}^{(e)} dx_j = \int_{-\frac{1}{2}}^{\frac{1}{2}} \left(\frac{\nabla_a y^{(e)} - b^{(e)}}{h^2} \right)_{ij}$$

$$= (\nabla' u)_{ij} + \left(\frac{R^{(e)} - \text{Id}}{h^2} \right)_{ij}$$

Now take sym and $B + h \rightarrow 0$.

□

Upper bound Use ansatz + correction part

$$Q_2 \leq Q_3.$$