

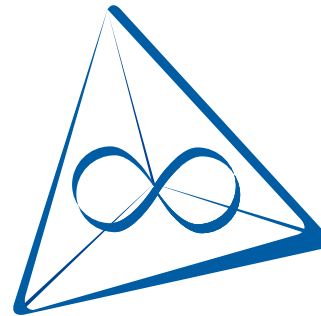
**INdAM Workshop “Nonconvex evolution
problems”**

Pattern formation & Partial Differential Equations

Felix Otto

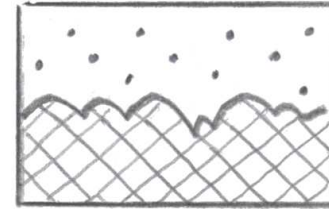
Max Planck Institute for Mathematics in the Sciences

Leipzig, Germany

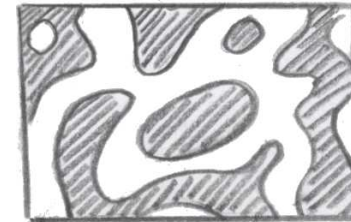


Pattern formation for two specific examples

A) crystal growth under deposition
— roughness of crystal surface



B) demixing of polymers
— labyrinth-like pattern
of concentration field



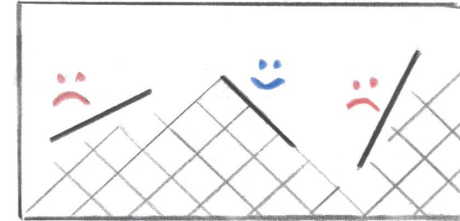
Few elementary mechanisms (diffusion, viscosity, ...)
— complex Pattern

Crystal growth and Kuramoto-Sivashinsky equation

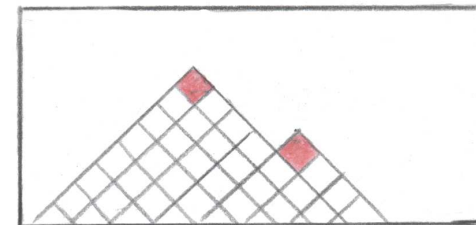
L. Giacomelli, D. Goldman

Relevant mechanisms

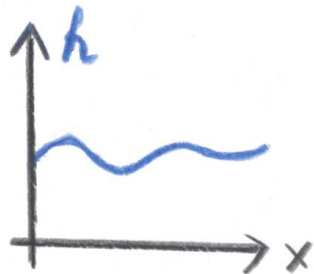
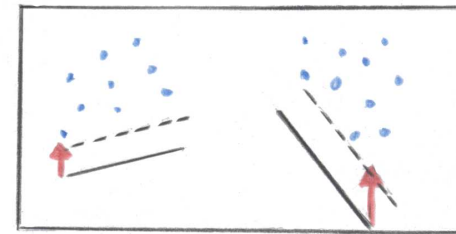
Crystal lattice favors certain slopes of the surface



Exposed positions are disfavored



Vertical growth rate depends on slope



$$\frac{\partial h}{\partial t} = \underbrace{-\frac{\partial}{\partial x} \left(\left(1 - \left(\frac{\partial h}{\partial x} \right)^2 \right) \frac{\partial h}{\partial x} \right)}_{\text{Surface energy term}} \underbrace{-\frac{\partial^4 h}{\partial x^4}}_{\text{Surface diffusion term}} \underbrace{+ f \left(1 + \frac{1}{2} \left(\frac{\partial h}{\partial x} \right)^2 \right)}_{\text{Source term}}$$

Qualitatively different behavior for small/large deposition rate f

Initial data $h(t = 0) =$ white noise of small amplitude

Deposition rate $f \ll 1$

- slow growth
- facets with preferred slope ± 1
- number of facets decreases

Deposition rate $f \gg 1$

- fast growth
- slope $\ll 1$
- number of maxima/minima \approx constant

“Convective” Cahn-Hilliard equation

Express equation for height h

$$\frac{\partial h}{\partial t} - f \left(1 + \frac{1}{2} \left(\frac{\partial h}{\partial x}\right)^2\right) + \frac{\partial}{\partial x} \left(\left(1 - \left(\frac{\partial h}{\partial x}\right)^2\right) \frac{\partial h}{\partial x} \right) + \frac{\partial^4 h}{\partial x^4} = 0$$

in terms of slope $u = -\frac{\partial h}{\partial x}$

$$\frac{\partial u}{\partial t} + f \frac{\partial}{\partial x} \left(\frac{1}{2} u^2\right) + \frac{\partial^2}{\partial x^2} \left((1 - u^2) u \right) + \frac{\partial^4 u}{\partial x^4} = 0$$

For large deposition rate $f \gg 1$ rescale $u = \frac{1}{f} \hat{u}$:

$$\frac{\partial \hat{u}}{\partial t} + \frac{\partial}{\partial x} \left(\frac{1}{2} \hat{u}^2\right) + \frac{\partial^2}{\partial x^2} \left(\left(1 - \frac{1}{f^2} \hat{u}^2\right) \hat{u} \right) + \frac{\partial^4 \hat{u}}{\partial x^4} = 0$$

**Regime of strong deposition:
Kuramoto-Sivashinsky equation**

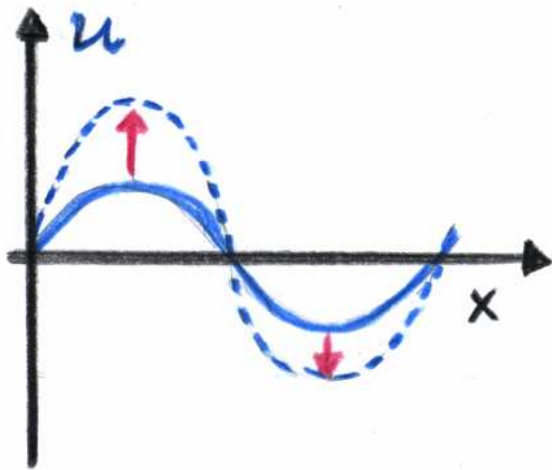
For $f \gg 1$, expressed in $u = -\frac{\partial h}{\partial x}$:

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} \left(\frac{1}{2} u^2 \right) + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^4 u}{\partial x^4} = 0$$

Three terms — three simple mechanisms

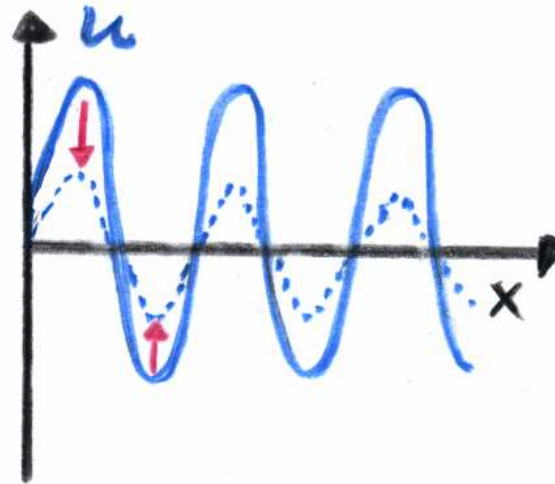
$$\frac{\partial^2 u}{\partial x^2}$$

Growth



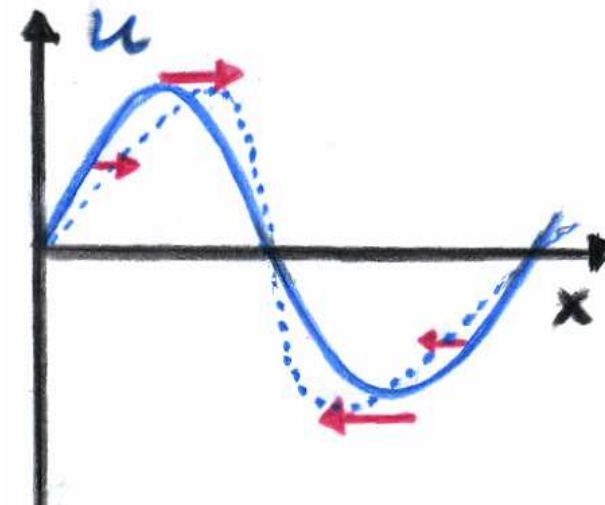
$$\frac{\partial^4 u}{\partial x^4}$$

Decay



$$\frac{\partial}{\partial x} \left(\frac{1}{2} u^2 \right)$$

Shear



Periodic configurations $u(t, x + L) = u(t, x)$; large system $L \gg 1$

Dynamic equilibrium

Initial data: $u(t = 0) =$ white noise of small amplitude

Observations:

Initial phase

- 1. Smoothing $(\frac{\partial^4 u}{\partial x^4})$
- 2. Growth $(\frac{\partial^2 u}{\partial x^2})$
- 3. Shear $(\frac{\partial}{\partial x}(\frac{1}{2}u^2))$

Dynamic equilibrium

- average amplitude ~ 1
- average wave length ~ 1
- chaotic behavior
in space & time

Shear contains exponential growth

Energy spectrum

Decomposition of spatial signal into waves of length $L, \frac{L}{2}, \frac{L}{3}, \dots$:

$$(\mathcal{F}u(t, \cdot))(k) := L^{-1} \int_0^L e^{ikx} u(t, x) dx \quad (\text{Fourier series})$$



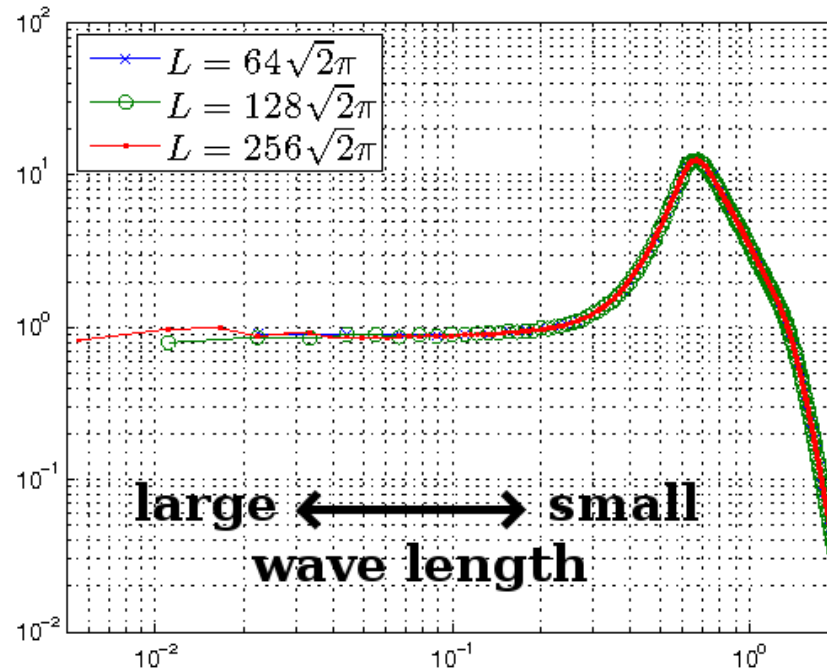
Contribution of wave number $(k, k + dk)$ to total energy:

$$L |(\mathcal{F}u(t, \cdot))(k)|^2 dk$$

Time average:

$$\lim_{t_0 \uparrow \infty} t_0^{-1} \int_0^{t_0} L |(\mathcal{F}u(t, \cdot))(k)|^2 dt$$

Equipartition of energy



Observations:

- Equipartition of energy over wave numbers $|k| \ll 1$
- Energy spectrum independent of $L \gg 1$

“Universal” behavior

Challenge for mathematics

Observation:

After initial phase, there is a dynamic equilibrium, with statistics independent of the initial data $u(t=0)$ and of the system size L

Challenge for theory of partial differential equations:

Why?

In mathematics: “Why ?” = “**How can it be proved?**”

A good proof gives **insight** into “why”

Modest state of mathematical insight

Only statements of the following form have been proved:

space-time averages of $|u|$, $|\frac{\partial u}{\partial x}|$, $|\frac{\partial^2 u}{\partial x^2}| \lesssim 1$,

for all initial data $u(t=0)$, system sizes L

These statements have been proved step-by-step:

space-time averages of $|u|$, $|\frac{\partial u}{\partial x}|$, $|\frac{\partial^2 u}{\partial x^2}| \lesssim L^p$,

for all initial data $u(t=0)$

Nicolaenko & Scheurer & Temam '85, Goodman '94: $\lesssim L^2$

Collet & Eckmann & Epstein & Stubbe '93: $\lesssim L^{11/10}$

Bronski & Gambill '06: $\lesssim L$, Giacomelli & O. '05: $\ll L$

O. '09 $\lesssim \ln^{5/3} L$

\rightsquigarrow bounds on **dim**(Attractor), **dim**(Inertial Manifold), Foias et. al.

Near-extensive bound

Theorem [O., JFA '09]

For any $\sigma > 5/3$ there exists $C < \infty$ such that for all $L \geq 2$, all initial data $u(0)$ and $\alpha \in [\frac{1}{3}, 2]$ we have

$$\left(\lim_{T \uparrow \infty} T^{-1} L^{-1} \int_0^T \int_0^L \left| |\partial_x|^\alpha u \right|^2 dx dt \right)^{1/2} \leq C \ln^\sigma L.$$

Insight from proof

Three methods have been developed. Insight of last method:

Shear term $\frac{\partial}{\partial x}(\frac{1}{2}u^2)$ behaves like a *coercive* term, i. e.

$$\int_0^L \frac{\partial}{\partial x}(\frac{1}{2}u^2) u \, dx \quad \text{as} \quad \int_0^L \left| \left| \frac{\partial}{\partial x} \right|^{1/3} u \right|^3 \, dx$$

despite actually being *conservative*, i. e.

$$\int_0^L \frac{\partial}{\partial x}(\frac{1}{2}u^2) u \, dx = 0.$$

Conservative acts as coercive in forced inviscid Burgers

Consider $f(t, x), g(t, x)$ with $\frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(\frac{1}{2}u^2) = \frac{\partial g}{\partial x}$,
smooth, periodic in x , compactly supported in t . Then

$$\iint \left| \left| \frac{\partial}{\partial x} \right|^{\frac{1}{3}} u \right|^3 dx dt \underset{\substack{\lesssim \\ \text{mod} \\ \log}}{\sim} \iint \left| \left| \frac{\partial}{\partial x} \right|^{\frac{2}{3}} g \right|^{\frac{3}{2}} dx dt,$$

more precisely expressed in interpolation spaces

(Goldman & O.)

$$\|u; [\dot{H}_{\infty}^1, L_2]_{\frac{1}{3}, \infty}\|^3 \lesssim \|g; [\dot{H}_2^1, L_1]_{\frac{2}{3}, 1}\|^{\frac{3}{2}}.$$

Connection with Onsager's conjecture on level of forced viscous Burgers

On the one hand, for $\frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(\frac{1}{2}u^2) - \nu \frac{\partial^2 u}{\partial x^2} = \frac{\partial g}{\partial x}$ have
uniform estimate in $\nu \downarrow 0$

$$\|u; [\dot{H}_{\infty}^1, L_2]_{\frac{1}{3}, \infty}\|^3 + \nu \|u; \dot{H}_2^1\|^2 \lesssim \|g; [\dot{H}_2^1, L_1]_{\frac{2}{3}, 1}\|^{\frac{3}{2}}.$$

On the other hand, at $\nu = 0$ if $u \in [\dot{H}_{\infty}^1, L_2]_{\frac{1}{3}, p}$ with
 $p < \infty$, would have *conservation of energy*

$$\frac{d}{dt} \int \frac{1}{2} u^2 dx = \int u \frac{\partial g}{\partial x} dx.$$

B. Demixing and Cahn-Hilliard equation

R. V. Kohn, Brenier & Seis, Seis & Slepcev

Cahn–Hilliard equation

conserved order parameter:

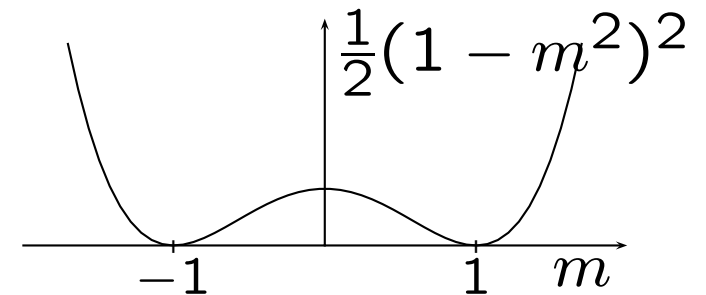
$$\partial_t m + \nabla \cdot j = 0$$

diffusion flux: $j = -\nabla \frac{\partial E}{\partial m}$

free energy: $E(m)$

$$= \int \frac{1}{2} |\nabla m|^2 + \frac{1}{2} (1 - m^2)^2 dx$$

periodic b.c. in $(0, L)^n$ with $L \gg 1$



Cahn–Hilliard equation with flow

Fluid flow next to diffusion

$$\partial_t m + \nabla \cdot j + \nabla \cdot (mu) = 0$$

where $j = -\lambda \nabla \frac{\partial E}{\partial m}$ and velocity u is determined by Stokes

$$-\Delta u + \nabla p = -m \nabla \frac{\partial E}{\partial m} \quad \text{and} \quad \nabla \cdot u = 0$$

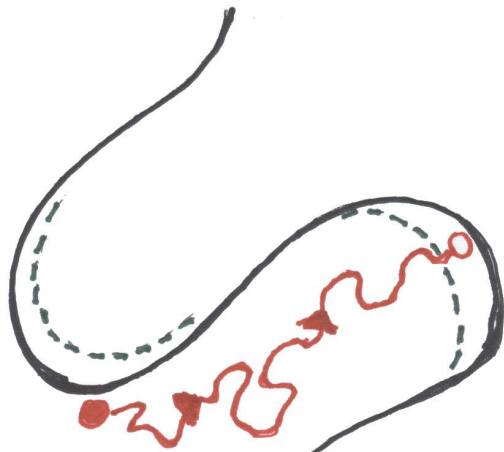
Non-dimensional mobility parameter $\lambda \gg 1$

Thermodyn. consistent: $\frac{dE}{dt} = -\frac{1}{\lambda} \int |j|^2 dx - \int |\nabla u|^2 dx$

Dissipation mechanism influences dynamics

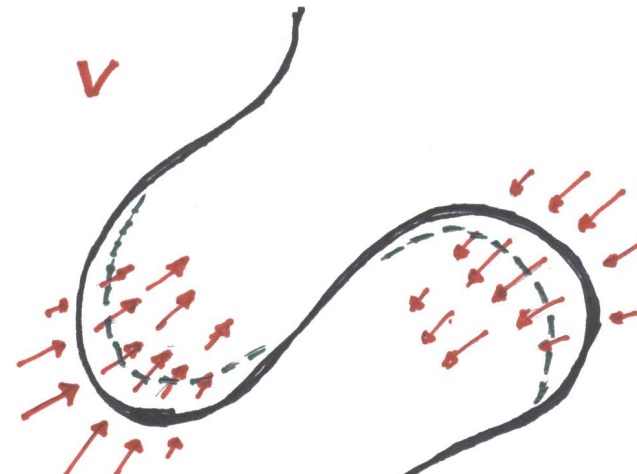
Energy functional $E \approx \frac{4}{3}$ area of transition layer

mediated by diffusion,
limited by outer friction



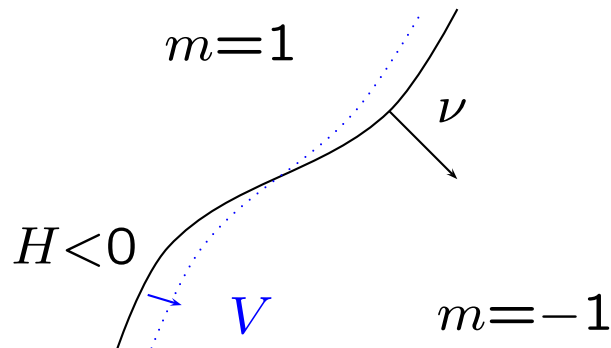
“Evaporation-
Recondensation”

mediated by flow,
limited by viscosity



“Siggia’s growth”

Geometric evolution equation, diffusion only



mean curvature: H

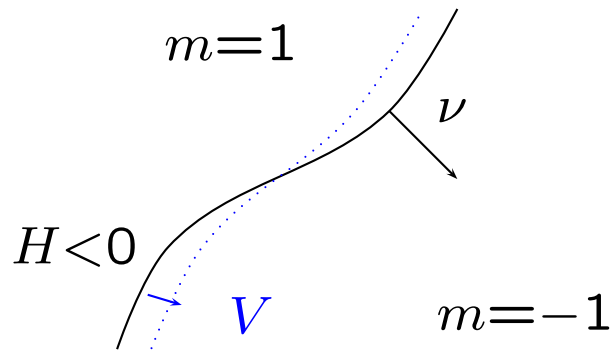
normal velocity: V

$$-\Delta\mu = 0 \quad \text{in bulk,} \quad \left\{ \begin{array}{l} \mu = \frac{2}{3}H \\ V = [\nu \cdot \nabla\mu] \end{array} \right\} \quad \text{on interface}$$

“Mullins-Sekerka”; Pego, Alikakos&Bates&Chen, Röger & Schätzle

Third-order free boundary problem

Geometric evolution equation, flow only



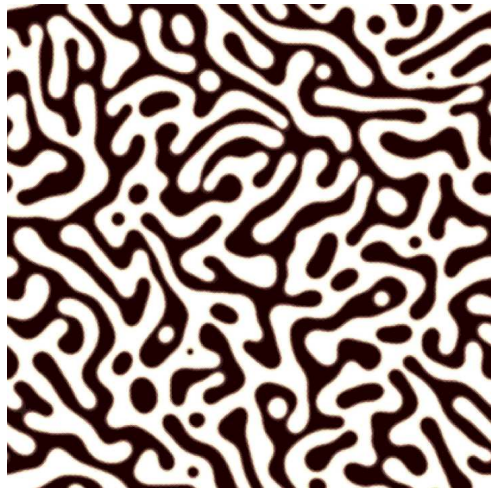
$$\left\{ \begin{array}{l} \nabla \cdot u = 0 \\ -\nabla \cdot S = 0 \end{array} \right\} \text{ in bulk, } \left\{ \begin{array}{l} \tau \cdot [S]\nu = 0 \\ \nu \cdot [S]\nu = -\frac{4}{3}H \\ V = \nu \cdot u \end{array} \right\} \text{ on interface,}$$

where $S := \frac{1}{2}(\nabla u + \nabla^t u) - p \text{id}$ is stress tensor

First-order free boundary problem

Statistical self-similarity

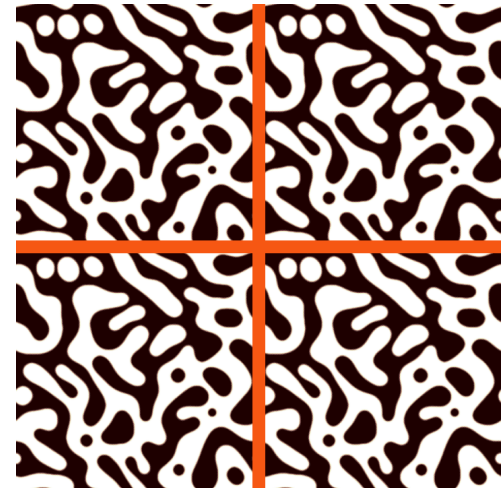
earlier



later



later,
rescaled,
periodically
extended



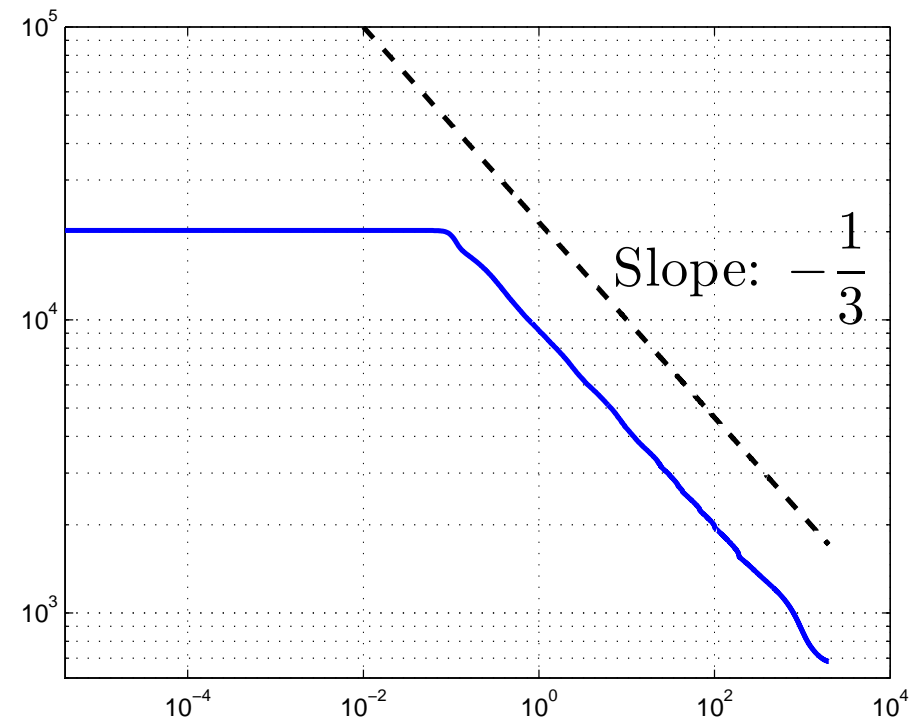
Diffusion dominated: coarsening exponent 1/3

After initial phase: Energy $E(m) \approx \frac{4}{3}$ area of transition layer

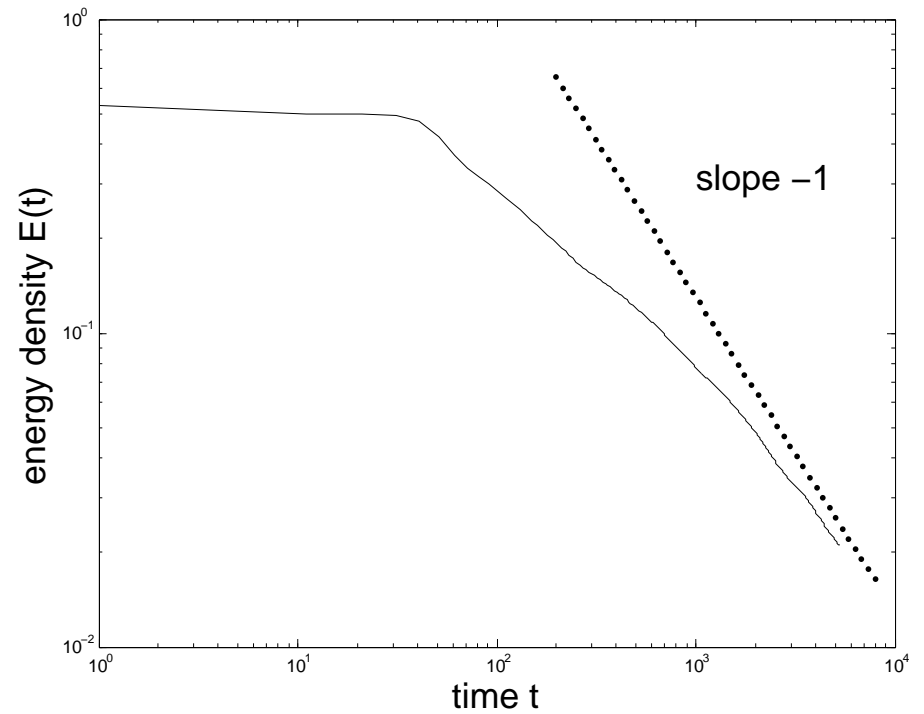
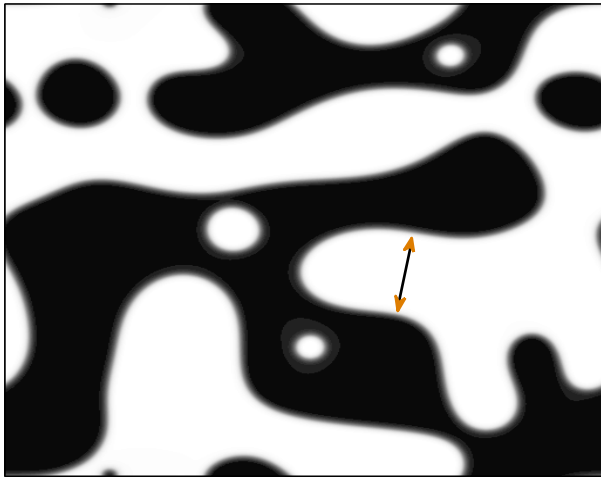
Hence $\left(\frac{1}{L^n} E(m)\right)^{-1}$ is an *average length scale*

Energy E vs. time t ,
double logarithmic plot:

$$L^{-(n=2)} E(m) \sim t^{-1/3}$$



Flow dominated: coarsening exponent 1



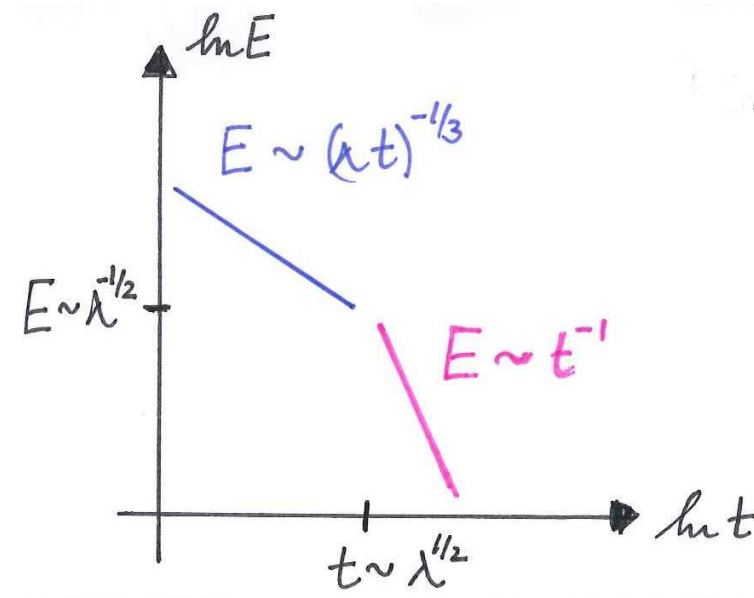
$$L^{-(n=2)} E(u) \sim t^{-1}$$

Cross-over from $t^{-1/3}$ to t^{-1}

Heuristics(Siggia '79): *Faster* mechanism dominates

initially: Diffusion faster

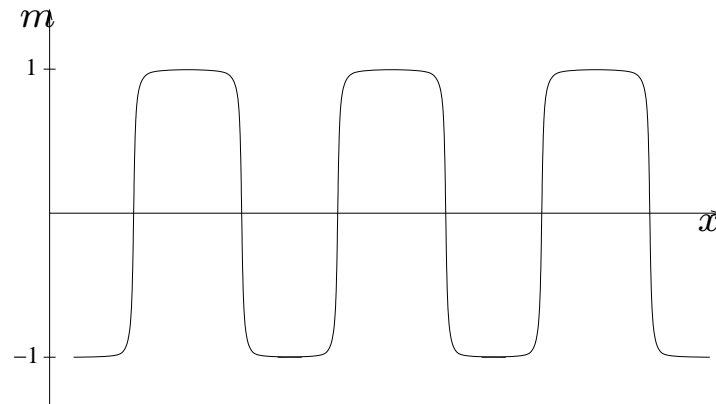
later: Flow faster



... confirmed by experiments

**Rigorous treatment
has to cope with ungeneric behavior**

Upper bounds on E not independent of initial data:
— too many stationary points of E



Lower bounds on E independent of initial data

Basic idea for rigorous lower bounds on E

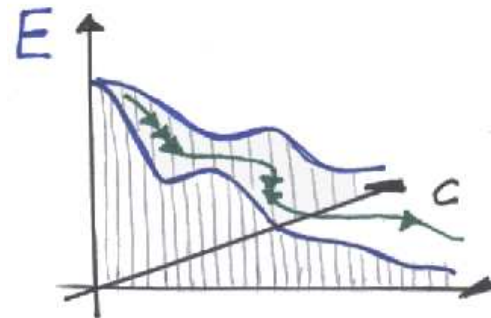
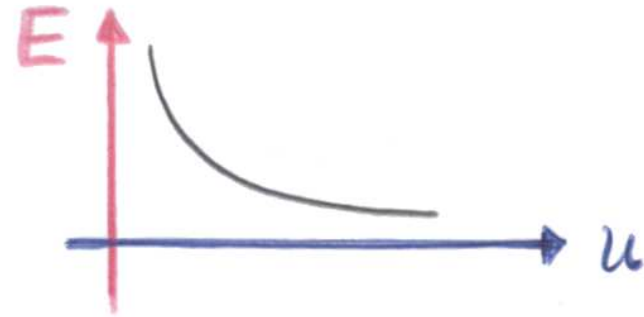
Dynamics is steepest descent
in energy landscape

energy \leftrightarrow heights,
dissipation
mechanism \leftrightarrow distances

landscape *not steep*

\implies

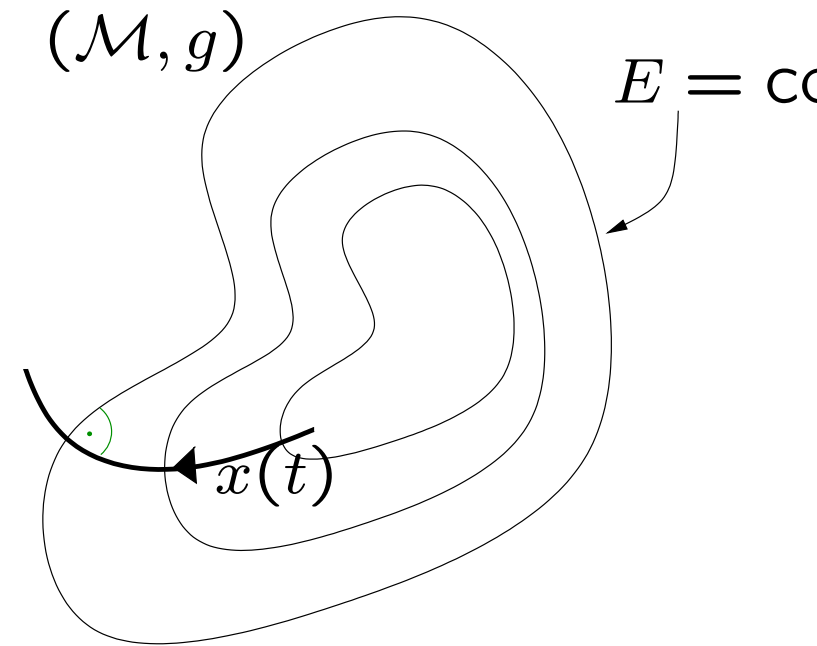
energy decreases *not fast*



An abstract framework

(\mathcal{M}, g) Riemannian manifold
 E functional on \mathcal{M}

Gradient flow $\dot{x} = -\text{grad}_g E(x)$



metric tensor $g_x(\delta x, \delta x)$ \rightsquigarrow induced distance $d(x_0, x_1)$
local *global*

Relating geometry to dynamics

Lemma. (Kohn & O. '02)

Assume for some $\alpha > 0$ and $x^* \in \mathcal{M}$

$$E(x) \gtrsim d(x^*, x)^{-\alpha} \quad \text{provided } E(x) \leq 1$$

Then for all $\sigma \in (1, \frac{\alpha+2}{\alpha})$

$$\int_0^T E(x(t))^\sigma dt \gtrsim \int_0^T (t^{-\frac{\alpha}{\alpha+2}})^\sigma dt \quad \text{for } T \gg d(x^*, x(0))^{\alpha+2}$$

and $E(x(0)) \leq 1$.

Type of dissipation determines metric tensor g

Transport mechanism type of dissipation:
diffusion \rightsquigarrow outer friction,
flow \rightsquigarrow inner friction (viscosity).

$$g_m(\delta m, \delta m) = \inf \left\{ \frac{1}{\lambda} \int |j|^2 dx + \int |\nabla u|^2 dx \mid \delta m + \nabla \cdot j + \nabla \cdot (m u) = 0, \nabla \cdot u = 0 \right\}.$$

... but induced distance d not explicitly known

Lower bound D

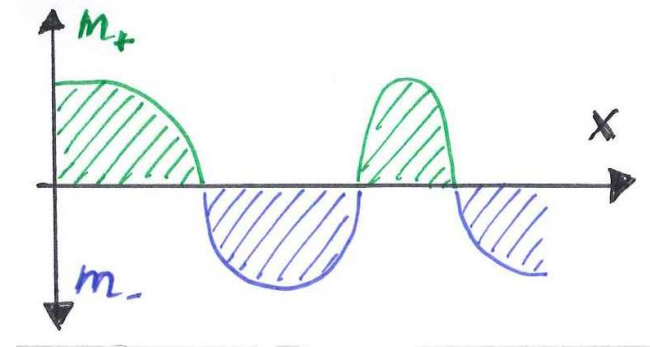
on induced distance d to reference configuration m^*

Reference configuration: well-mixed state $m^* = 0$

Lower bound $D(m)$ to induced distance $d(m, m^*)$
given by **transportation distance**

between $m_+ := \max\{m, 0\}$

and $m_- := \max\{-m, 0\}$

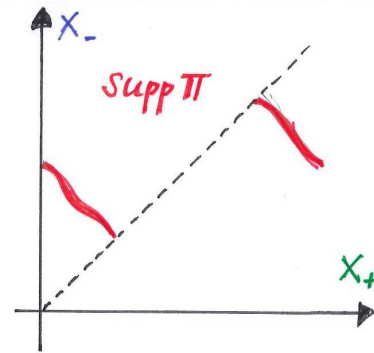
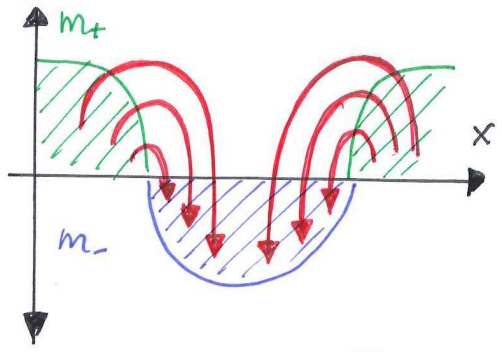


Definition of transportation distance D

Given $m = m_+ - m_-$, measure $\pi(dx_- dx_+)$ on $[0, L]^n \times [0, L]^n$ is called **admissible transfer plan** provided

$$\int \zeta(x_+) \pi(dx_+ dx_-) = \int \zeta(x) m_+(x) dx,$$

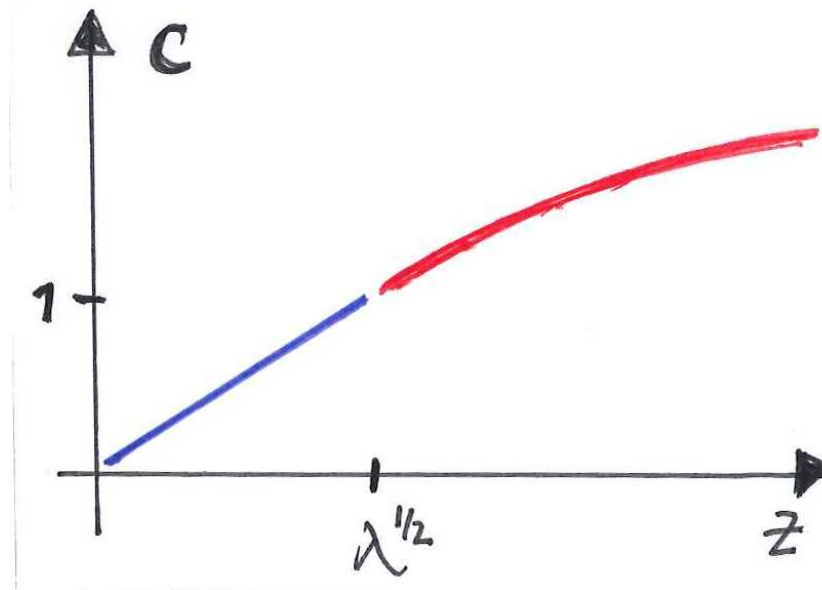
$$\int \zeta(x_-) \pi(dx_+ dx_-) = \int \zeta(x) m_-(x) dx.$$



$$D(m) := \inf \left\{ \int c(|x_- - x_+|) \pi(dx_+ dx_-) \mid \pi \text{ admissible} \right\}$$

Choice of cost c

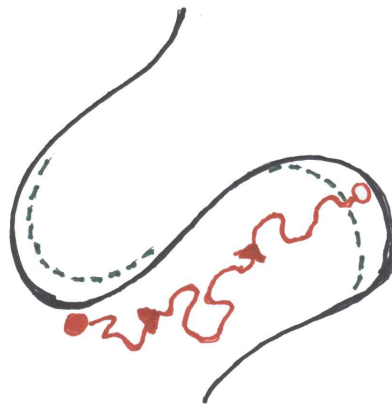
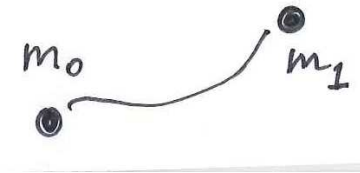
cross-over between **linear** and **logarithmic** at $z = \lambda^{1/2}$



$$c(z) := \left\{ \begin{array}{ll} \frac{z}{\lambda^{1/2}} & \text{for } z \leq \lambda^{1/2} \\ 1 + \ln \frac{z}{\lambda^{1/2}} & \text{for } z \geq \lambda^{1/2} \end{array} \right\}$$

Dissipation mechanism determines geometry

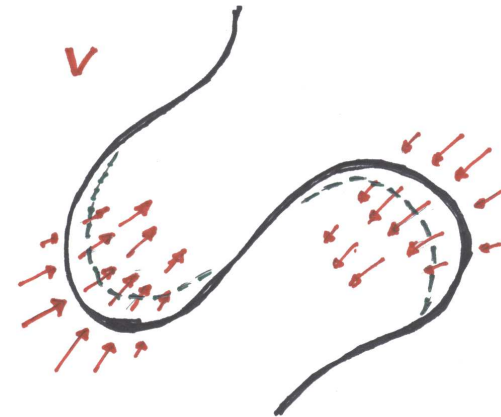
Distance on configuration space



diffusion

transportation
distance with cost

$$c(x_- - x_+) \\ = |x_- - x_+|$$



flow

transportation
distance with cost

$$c(x_- - x_+) \\ = \ln(1 + |x_- - x_+|)$$

Main result

Theorem. (O. & Seis & Slepcev '10+, Brenier, O. & Seis '10)

For any solution u with $\lambda \gg 1$, $L \gg 1$,

$$\int_0^T \max\left\{\lambda^{\frac{1}{2}}\left(\frac{E}{L^n}\right)^2, \frac{E}{L^n}\right\} dt \gtrsim \min\left\{\left(\frac{T}{\lambda^{\frac{1}{2}}}\right)^{1/3}, 1 + \ln\left(1 + \frac{T}{\lambda^{\frac{1}{2}}}\right)\right\}$$

provided

$$\frac{E(0)}{L^n} \lesssim 1 \quad \text{and} \quad \frac{T}{\lambda^{\frac{1}{2}}} \gg \left(\frac{D(0)}{\lambda^{\frac{1}{2}}}\right)^3 \quad (\gtrsim 1).$$

Dissipation: $D(m)$ is lower bound to $d(m, m^*)$

Dissipation Lemma (BOS, OSS).

Suppose

$$\begin{aligned}\partial_t m + \nabla \cdot j + \nabla \cdot (mu) &= 0, \\ \nabla \cdot u &= 0.\end{aligned}$$

Then provided $\frac{1}{L^n} E(m) \lesssim 1$

$$\left(\frac{1}{L^n} \frac{d}{dt} D(m) \right)^2 \lesssim \lambda^{-1} \frac{1}{L^n} \int |j|^2 dx + \frac{1}{L^n} \int |\nabla u|^2 dx.$$

Uses idea of Crippa-DeLellis ('08)

for quantification of DiPerna-Lions theory

on uniqueness for transport equations $\partial_t m + u \cdot \nabla m = 0$

Future directions

Local estimates

Example with cross-over due to dissipation mechanisms

“in series”, like diffusion+attachment-limited

— instead of “in parallel”, like diffusion+flow-mediated (Dai&Pego
on LSW-level)

Future directions

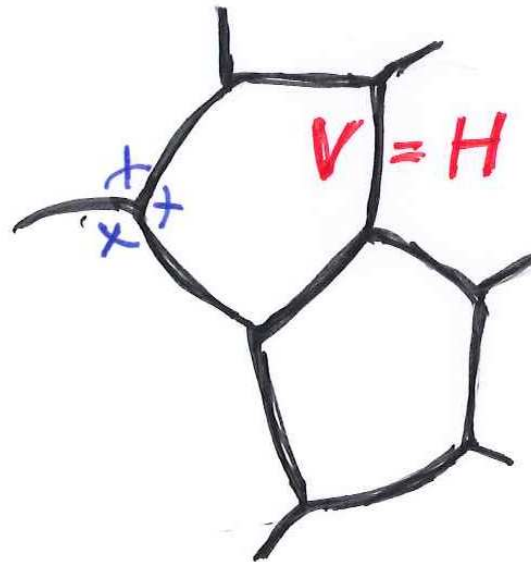
Grain growth

= aging in polycrystals

= multi-component

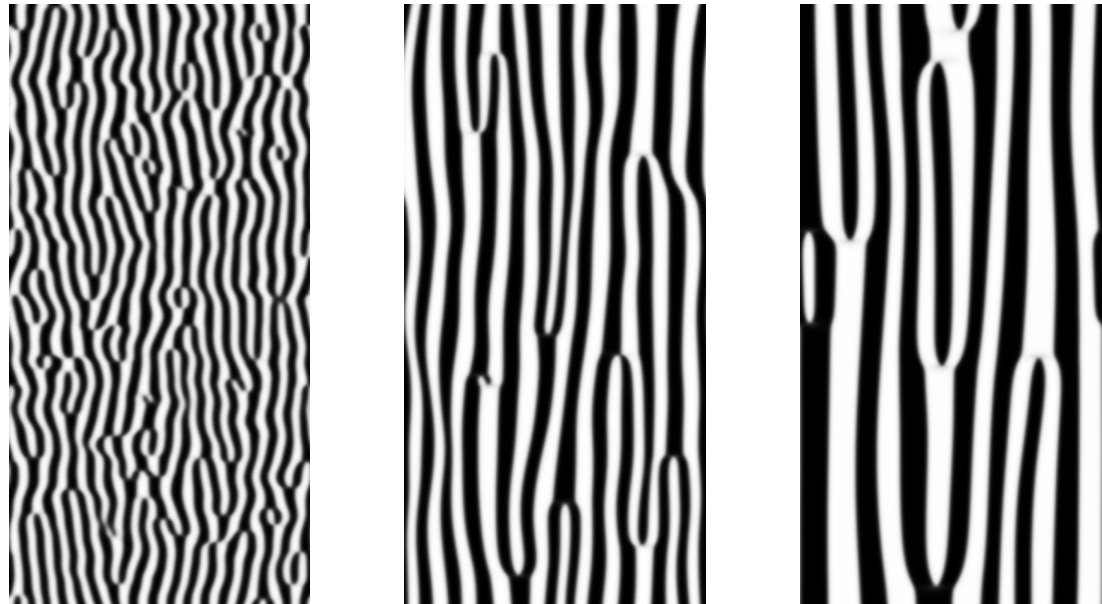
mean curvature flow

$$\frac{1}{L^n} E \gtrsim t^{-1/2}$$



Future directions

Defect-mediated
coarsening
(e.g. in
Siegert's model
for crystal growth)



Upper bounds on E for *generic* initial data